

# Marginal Deformations and 3-Algebra Structures

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Based on:

- S. A. Cherkis, CS, [PRD 78 \(2008\) 066019](#)
- S. A. Cherkis, V. Dotsenko, CS, [PRD 79 \(2009\) 086002](#)
- N. Akerblom, CS and M. Wolf, [Nucl. Phys. B \(2009\) ...](#)

- **Introductory part**
  - The **Nahm** equation or **D1-D3** branes
  - The **Basu-Harvey** equation or **M2-M5** branes
  - **3-Lie algebras**
  - **Stacks** of flat **M2**-branes: The **BLG** model
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- **Deformations** preserving  $\mathcal{N} = 2$  supersymmetry
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# The Nahm Equation or D1-D3-Branes

In type IIB string theory, monopoles can be seen as D1-branes ending on D3-branes.

Consider a **D3-brane** in directions **0234**.

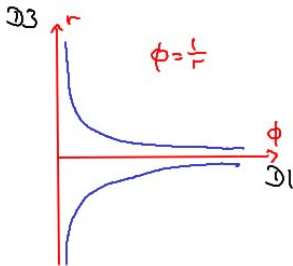
A BPS solution to the SYM equations is the magnetic monopole with Higgs field

$\phi \sim \frac{1}{r}$ : A **D1-brane** appears.

As they are BPS, one trivially forms a stack of  $N$  **D1-branes**.

From the perspective of the **D1-brane**, the effective dynamics is described by the **Nahm equations**:

$$\frac{d}{d\phi} X^i + \varepsilon^{ijk} [X^j, X^k] = 0 .$$



	dim	0	1	2	3	4
D1		×	×			
D3		×		×	×	×

These equations have the following solution (“**fuzzy funnel**”)

$$X^i = r(\phi) G^i , \quad r(\phi) = \frac{1}{\phi} , \quad G^i = \varepsilon^{ijk} [G^j, G^k]$$

# The Basu-Harvey Equation or M2-M5-Branes

M2 branes ending on M5 branes should be described by Nahm-type equations.

**M5-brane** in directions 013456:

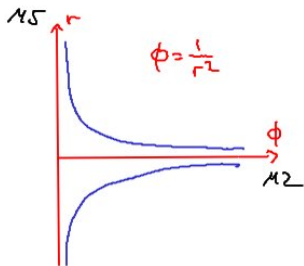
$$G^{mn} \nabla_m \nabla_n X^{a'} = 0$$

$$G^{mn} \nabla_m H_{npq} = 0$$

Ansatz for a soliton:

$$X^{5'} = \phi$$

$$H_{01m} = v_m \quad H_{mnp} = \varepsilon_{mnpq} v^q$$



Solution:

$$H_{01m} \sim \partial_m \phi \quad \phi \sim \frac{1}{r^2}$$

	dim	0	1	2	3	4	5	6
M2		×	×					×
M5		×		×	×	×	×	×

**Perspective of M2:** postulate four scalar fields  $X^i$ , satisfying

$$\frac{d}{d\phi} X^i + \varepsilon^{ijkl} [X^j, X^k, X^l] = 0$$

Basu, Harvey, hep-th/0412310

# The Basu-Harvey Equation or M2-M5-Branes

M2 branes ending on M5 branes should be described by Nahm-type equations.

Basu-Harvey equation:

$$\frac{d}{d\phi} X^i + \varepsilon^{ijkl} [X^j, X^k, X^l] = 0$$

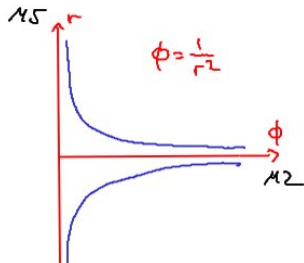
**Solution** (similar to D1-D3 case):

$$X^i = r(\phi) G^i \quad r(\phi) = \frac{1}{\sqrt{\phi}}$$

$$G^i = \varepsilon^{ijkl} [G^j, G^k, G^l]$$

Interprete this again as a **fuzzy funnel**, this time with a fuzzy  $S^3$  at every point  $\phi$  (not quite...).

$$R \sim \sqrt{N} \quad \text{dofs} \sim R^3 \sim N^{3/2} \quad \checkmark$$



dim	0	1	2	3	4	5	6
M2	×	×				×	
M5	×		×	×	×	×	×

# What is the algebra behind the triple bracket?

In analogy with Lie algebras, we can introduce 3-Lie algebras.

Basu-Harvey equation:

$$\frac{d}{d\phi} X^i + \varepsilon^{ijkl} [X^j, X^k, X^l] = 0, \quad X^i(\phi) \in \mathcal{A}$$

- ▷  $\mathcal{A}$  forms a **vector space**.
- ▷  $[\cdot, \cdot, \cdot]$  is a totally antisymmetric, linear map  $\mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \rightarrow \mathcal{A}$ .

# What is the algebra behind the triple bracket?

In analogy with Lie algebras, we can introduce 3-Lie algebras.

Basu-Harvey equation:

$$\frac{d}{d\phi} X^i + [A_\phi, X^i] + \varepsilon^{ijkl} [X^j, X^k, X^l] = 0, \quad X^i \in \mathcal{A}$$

▷ Gauge transformations from **inner derivations**:

The triple bracket forms a map  $\delta : \mathcal{A} \wedge \mathcal{A} \rightarrow \text{Der}(\mathcal{A}) =: \mathfrak{g}_{\mathcal{A}}$  via

$$\delta_{A \wedge B}(C) := [A, B, C]$$

Demand a **“3-Leibniz rule”**:

$$\begin{aligned} \delta_{A \wedge B}(\delta_{C \wedge D}(E)) &:= [A, B, [C, D, E]] \\ &= [[A, B, C], D, E] + [C, [A, B, D], E] + [C, D, [A, B, E]] \end{aligned}$$

The inner derivations form indeed a **Lie algebra**:

$$[\delta_{A \wedge B}, \delta_{C \wedge D}](E) := \delta_{A \wedge B}(\delta_{C \wedge D}(E)) - \delta_{C \wedge D}(\delta_{A \wedge B}(E))$$

Bracket closes due to **“3-Leibniz rule”**.

# What is the algebra behind the triple bracket?

In analogy with Lie algebras, we can introduce 3-Lie algebras.

To write down an action, i.e. gauge invariant terms, we need an **invariant pairing** on  $\mathcal{A}$ :

$$(\cdot, \cdot) : \mathcal{A} \otimes \mathcal{A} \rightarrow \mathbb{C}$$

**Invariance** under gauge transformations:

$$([A, B, C], D) + (C, [A, B, D]) = 0$$

On  $\text{Der}(\mathcal{A})$ , there are now **two** pairings  $((\cdot, \cdot))$ :

1. The usual **Killing form**
2. A pairing induced from the pairing on  $\mathcal{A}$ :

$$((\delta_{A \wedge B}, \delta_{C \wedge D})) = (D, [A, B, C])$$

Key to constructing a maximally SUSY model later: **use the latter**.



## Short Remark: $L_\infty$ -algebras

This structures form a simple strong homotopy Lie algebra.

Note: we could combine  $\mathcal{A}$  and  $\text{Der}(A)$  into one space  $\mathcal{V}$  with two brackets  $[\cdot, \cdot]$  and  $[\cdot, \cdot; \cdot]$ .

Jacobi-Identity and 3-Leibniz rule  $\leftrightarrow$  Homotopy Jacobi identities.

$\mathcal{V}$  forms therefore an  $L_\infty$ - or strong homotopy Lie algebra.

The Basu-Harvey equation is then precisely the homotopy Maurer-Cartan equation for the  $L_\infty$  algebra  $\mathcal{V} \otimes \Omega^\bullet(\mathbb{R})$ .

$L_\infty$  algebras are behind most things coming up. Usefulness unclear.

C. I. Lazaroiu, D. McNamee, CS and A. Zejak, 0901.3905

# Example: The Metric 3-Lie Algebra $A_4$

The 3-Lie algebra  $A_4$  is the most important 3-Lie algebra in the context of BLG.

Consider the vector space  $\mathbb{R}^4$  with basis  $\tau_1, \dots, \tau_4$ .

Then define the bracket  $[\cdot, \cdot, \cdot]$  as the linear extension of

$$[\tau_a, \tau_b, \tau_c] = \sum_d \varepsilon_{abcd} \tau_d \quad .$$

Additional structure:

The bilinear symmetric map  $(\cdot, \cdot)$  is given as the lin. extension of

$$(\tau_a, \tau_b) = \delta_{ab} \quad .$$

The **associated Lie algebra** is  $\mathfrak{g}_{A_4} = \mathfrak{so}(4) \cong \mathfrak{su}(2) \times \mathfrak{su}(2)$ ;

its bilinear pairing  $((\cdot, \cdot))$  has **split signature**:

$$((\delta_{\tau_a \wedge \tau_b}, \delta_{\tau_c \wedge \tau_d})) = \varepsilon_{abcd}$$

# Approaching the Effective Description of M2-Branes

Spacetime symmetries and BPS equations give helpful constraints on the description.

A stack of flat **M2-branes** in  $\mathbb{R}^{1,10}$  should be effectively described by a conformal field theory with the following constraints:

Spacetime symmetries:  $SO(1, 10) \rightarrow SO(1, 2) \times SO(8)$   
extended by  $\mathcal{N} = 8$  **SUSY**.

Field content:  $X = \Gamma_I X^I$ ,  $I = 1, \dots, 8$ , and superpartners  $\Psi_\alpha$

## Assumption

Take **BPS/SUSY transformations** from **Basu-Harvey** equation and therefore the matter fields take values in a **metric 3-Lie algebra**.

$$\delta X = i\Gamma_I \bar{\epsilon} \Gamma^I \Psi \quad \delta \Psi = \partial_\mu X \Gamma^\mu \epsilon - \frac{1}{6} [X, X, X] \epsilon$$

**Recipe:** Try to close SUSY algebra. Constraints yield equations of motion for matter fields.

# The Bagger-Lambert-Gustavsson Model

This model is an unconventional supersymmetric Chern-Simons matter theory.

BLG found that for **SUSY**, we need to introduce gauge symmetry.

⇒ Field content:  $X \in \mathcal{A}$ ,  $\Psi \in \mathcal{A}$  and gauge potential  $A_\mu \in \mathfrak{g}_\mathcal{A}$ .

## The Bagger-Lambert-Gustavsson model

$$\begin{aligned}\mathcal{L}_{\text{BLG}} = & + \frac{k}{4\pi} \varepsilon^{\mu\nu\kappa} \left( (A_\mu, \partial_\nu A_\kappa) + \frac{1}{3} (A_\mu, [A_\nu, A_\kappa]) \right) \\ & - \frac{1}{2} (\nabla_\mu X, \nabla^\mu X)_{Cl} + \frac{i}{2} (\bar{\Psi}, \Gamma^\mu \nabla_\mu \Psi) \\ & + \frac{i}{4} (\bar{\Psi}, [X, X, \Psi]) - \frac{1}{12} ([X, X, X], [X, X, X])_{Cl}\end{aligned}$$

This model is invariant under the supersymmetry transformations:

$$\begin{aligned}\delta X &= i\Gamma_I \bar{\varepsilon} \Gamma^I \Psi, & \delta \Psi &= \nabla_\mu X \Gamma^\mu \varepsilon - \frac{1}{6} [X, X, X] \varepsilon, \\ \delta A_\mu &= i\bar{\varepsilon} \Gamma_\mu (\delta X \wedge \Psi)\end{aligned}$$

# Consistency checks

The BLG model passes a number of consistency checks.

$$\begin{aligned}\mathcal{L}_{\text{BLG}} = & + \frac{k}{4\pi} \varepsilon^{\mu\nu\kappa} \left( (A_\mu, \partial_\nu A_\kappa) + \frac{1}{3} (A_\mu, [A_\nu, A_\kappa]) \right) \\ & - \frac{1}{2} (\nabla_\mu X, \nabla^\mu X)_{Cl} + \frac{i}{2} (\bar{\Psi}, \Gamma^\mu \nabla_\mu \Psi) \\ & + \frac{i}{4} (\bar{\Psi}, [X, X, \Psi]) - \frac{1}{12} ([X, X, X], [X, X, X])_{Cl}\end{aligned}$$

## Further results:

- The model is classically conformal and seems rather unique.
- If  $\mathcal{N} = 8$  SUSY not anomalous  $\Rightarrow$  vanishing  $\beta$ -function
- The model is parity invariant.
- Under some assumptions: reduction mechanism M2 $\rightarrow$ D2.

(Mukhi, Papageorgakis, 0803.3218)

- $k = 2$ : moduli space matches 2 M2-branes at tip of  $\mathbb{R}^8/\mathbb{Z}_2$ .
- Recast into the ABJM version, it yields integrable spin chain.

# Manifestly $\mathcal{N} = 2$ SUSY Formulation

There is a manifestly  $\mathcal{N} = 2$  SUSY formulation, allowing for various deformations.

**Approach:** Take  $\mathcal{N} = 1$ , 4d superspace  $\mathbb{R}^{1,3|4}$  and reduce to 3d.

Field content of the theory:

- The matter fields  $X^I$ ,  $\Psi$  are encoded in four chiral multiplets:

$$\Phi^i(y) = \phi^i(y) + \sqrt{2}\theta\psi^i(y) + \theta^2 F^i(y) ,$$

- The gauge potential  $A_\mu$  is contained in a vector superfield:

$$\begin{aligned} V(x) = & -\theta^\alpha \bar{\theta}^{\dot{\alpha}} (\sigma_{\alpha\dot{\alpha}}^\mu A_\mu(x) + i\varepsilon_{\alpha\dot{\alpha}} \sigma(x)) \\ & + i\theta^2 (\bar{\theta}\bar{\lambda}(x)) - i\bar{\theta}^2 (\theta\lambda(x)) + \frac{1}{2}\theta^2 \bar{\theta}^2 D(x) , \end{aligned}$$

$\mathcal{N} = 2$  superspace formulation of BLG (Cherkis, CS, 0807.0808)

$$\begin{aligned} \mathcal{L} = & \int d^4\theta \kappa (i\langle V, (\bar{D}_\alpha D^\alpha V) \rangle + \frac{2}{3} \langle V, \{(\bar{D}^\alpha V), (D_\alpha V)\} \rangle) \\ & + (\bar{\Phi}_i, e^{2iV} \cdot \Phi^i) + \alpha \left( \int d^2\theta \varepsilon_{ijkl} ([\Phi^i, \Phi^j, \Phi^k], \Phi^l) + c.c. \right) \end{aligned}$$

# Manifestly $\mathcal{N} = 4$ Supersymmetric Formulation

In projective superspace, one can make  $\mathcal{N} = 4$  SUSY in the BLG model manifest.

**Field content** of the BLG model in projective superspace:

- Matter  $X^I, \Psi$ : 4  $\mathcal{N} = 2$  **chiral mltps.**  $\Rightarrow$  2  $\mathcal{N} = 4$  **hypermultips.**
- Gauge  $A_\mu$ :  $\mathcal{N} = 2$  vector multiplet  $\Rightarrow$   $\mathcal{N} = 4$  **tropical multiplet**

Supersymmetric **action**: (Cherkis, Dotsenko, CS, 0812.3127)

$$\int \mu \kappa \left( i \langle \mathcal{V}, (\bar{\mathcal{D}}_\alpha \mathcal{D}^\alpha \mathcal{V}) \rangle + \frac{2}{3} \langle \mathcal{V}, \{ (\bar{\mathcal{D}}^\alpha \mathcal{V}), (\mathcal{D}_\alpha \mathcal{V}) \} \rangle \right) + (\bar{\eta}_k, e^{2i\mathcal{V}} \cdot \eta_k)$$

**Observations:**

- Chern-Simons term completely reduces to  $\mathcal{N} = 1$  form.
- The complex linear superfield  $\Sigma$  in the hypermultiplet
$$\eta_k = \bar{\Phi} \frac{1}{\zeta^2} + \bar{\Sigma} \frac{1}{\zeta} + X - \zeta \Sigma + \zeta^2 \Phi$$
can be dualized to a chiral multiplet.
- To compute the interaction terms, one would have to solve a **Riemann-Hilbert problem**. However, its **symmetries** tell us that this is the BLG model.

# Motivation: Marginal deformations of $\mathcal{N} = 4$ SYM

The BLG model shares features with  $\mathcal{N} = 4$  SYM. What about marginal deformations?

**Observation:** BLG/ABJM seems similar to  $\mathcal{N} = 4$  SYM  
( $\rightarrow$  integrable spin chains).

$\mathcal{N} = 4$  SYM admits (exactly) **marginal deformations:**

$$\mathcal{W} = \varepsilon_{ijk} \operatorname{tr}([\Phi^i, \Phi^j]_{\beta} \Phi^k)$$
$$[\Phi^i, \Phi^j]_{\beta} := e^{i\beta} \Phi^i \Phi^j - e^{-i\beta} \Phi^j \Phi^i$$

R. G. Leigh and M.J. Strassler, Nucl. Phys. B 447 (1995).

Conformality for  $\beta$ -deformed SYM to all orders in perturbation theory: S. Ananth, S. Kovacs, H. Shimada, JHEP 01 (2007) 046.

Such deformations correspond to deformations of  $AdS_5 \times S^5$ .

Similar deformations for  $AdS_4 \times S^7$  in the literature.

What about BLG/ABJM and their deformations on quantum level?



- **Introductory part**
  - The **Nahm** equation or **D1-D3** branes
  - The **Basu-Harvey** equation or **M2-M5** branes
  - **3-Lie algebras**
  - **Stacks** of flat **M2**-branes: The **BLG** model
  - **Superspace** formulations
  - **Motivation**: Marginal deformations of  $\mathcal{N} = 4$  **SYM theory**
- ▶ **More on 3-algebras**
  - **Real** and **Hermitian** 3-algebras
  - **Matrix** representations of 3-algebras
  - Associated **3-products**
- **Deformations** preserving  $\mathcal{N} = 2$  supersymmetry
  - Action in terms of  $\mathcal{N} = 2$  **superfields**
  - **Supergraph** Feynman rules
  - Results at two loops
- **Conclusions**

# Metric 3-Lie Algebras

3-Lie algebras come with a triple bracket and an induced Lie algebra structure.

metric 3-Lie algebras (Filippov, 1985)

$\mathcal{A}$  a real vector space with a bracket  $[\cdot, \cdot, \cdot] : \Lambda^3 \mathcal{A} \rightarrow \mathcal{A}$  satisfying

$$[A, B, [C, D, E]] = \\ [[A, B, C], D, E] + [C, [A, B, D], E] + [C, D, [A, B, E]] \quad (\text{FI})$$

and a bilinear symmetric map  $(\cdot, \cdot) : \mathcal{A} \otimes \mathcal{A} \rightarrow \mathbb{R}$  satisfying

$$([A, B, C], D) + (C, [A, B, D]) = 0 \quad (\text{Cmp})$$

There is a map from  $\mathcal{A} \wedge \mathcal{A}$  to  $\text{Der}(\mathcal{A})$  given by linearly extending

$$D_{A \wedge B}(C) := [A, B, C], \quad A, B, C \in \mathcal{A}$$

The inner derivations  $\mathfrak{g}_{\mathcal{A}} := \text{im}(D_{\mathcal{A} \wedge \mathcal{A}})$  form a Lie algebra.

Two invariant pairings on  $\mathfrak{g}_{\mathcal{A}}$ :  $(\delta_{A \wedge B}, \delta_{C \wedge D}) := ([A, B, C], D)$   
and induced Killing form.

# Extending The Structure of a 3-Lie Algebra

The notion of a 3-Lie algebra is too restrictive and one has to find a generalized notion.

**Problem:** Given a three-algebra  $\mathcal{A}$ , if its bilinear form  $(\cdot, \cdot)$  is positive definite, then  $\mathcal{A}$  is  $A_4$  or a direct sum thereof.

$A_4$  supposedly describes a stack of 2 M2-branes, not enough.

Mukhi, Papageorgakis, 0803.3218

**Possible extensions:**

- (1) Assume, 3-Lie algebras appear accidentally  $\Rightarrow$  ABJM model
- (2) Give up positive definiteness of  $(\cdot, \cdot) \Rightarrow$  ghosts
- (3) Relax conditions on 3-Lie algebras (+monopole operators)

Guideline: Demand **gauge invariance** of the  $\mathcal{N} = 2$  Lagrangian

$$\mathcal{L} = \int d^4\theta \kappa \left( i \langle V, (\bar{D}_\alpha D^\alpha V) \rangle + \frac{2}{3} \langle V, \{ (\bar{D}^\alpha V), (D_\alpha V) \} \rangle \right) \\ + (\bar{\Phi}_i, e^{2iV} \cdot \Phi^i) + \alpha \left( \int d^2\theta \varepsilon_{ijkl} ([\Phi^i, \Phi^j, \Phi^k], \Phi^l) + c.c. \right)$$

# Admissible 3-Algebraic Structures

Imposing gauge invariance in the  $\mathcal{N} = 2$  BLG-like model leads to more freedom.

Demanding **gauge invariance** in above theory yields the condition:

$$\begin{aligned}([A, B, C], D) &= -([B, A, C], D) \\ &= -([A, B, D], C) = ([C, D, A], B)\end{aligned}$$

Cherkis, CS, 0807.0808

Generalized metric 3-Lie algebras or real 3-algebras

Same as a 3-Lie algebra, but relax  $([A, B, C], D)$  from totally antisymmetric to the above symmetry properties.

# Hermitian 3-Lie Algebras

Another generalization of 3-Lie algebras are the Hermitian ones yielding  $\mathcal{N} = 6$  SUSY.

Alternatively to our way of extending 3-Lie algebras:

Reduce supersymmetry to  $\mathcal{N} = 6$ , i.e. assume the following:

$$\delta\phi^i = \sqrt{2}\bar{\varepsilon}^{ij}\bar{\psi}_j ,$$

$$\delta\bar{\psi}_i = -i\sqrt{2}\sigma^\mu\varepsilon_{ij}\nabla_\mu\phi^j + [\phi^j, \phi^k; \bar{\phi}_j]\varepsilon_{ik} + [\phi^j, \phi^k; \bar{\phi}_i]\varepsilon_{jk} ,$$

$$\delta A_\mu = -i\varepsilon_{ij}\sigma_\mu\phi^i \wedge \psi^j + i\bar{\varepsilon}^{ij}\sigma_\mu\bar{\phi}_i \wedge \bar{\psi}_j .$$

where  $\varepsilon^{ij}$  is in the **6** of  $SU(4)$ . Closure of this algebra implies:

$$[A, B; C] = -[B, A; C] \quad ([A, B; C], D) = (B, [C, D; A]) .$$

$$[[C, D; E], A; B] - [[C, A; B], D; E] - [C, [D, A; B]; E] + [C, D; [E, B; A]] = 0 .$$

An associated Lie algebra  $\mathfrak{g}_A := \text{im}(D_{A\otimes A})$  is induced by

$$D_{A\wedge B}(C) := [C, A; B] , \quad A, B, C \in \mathcal{A}$$

This leads to the ABJM model, a Chern-Simons-matter theory.

Aharony, Bergman, Jafferis, Maldacena, 0806.1218

Bagger, Lambert, 0807.0163

# Current Situation:

It is not clear, if 3-Lie algebras are necessary at all.

## Observations:

- 3-Lie algebras too restrictive, only one example:  $A_4$ .
- Generalizations lead to less than  $\mathcal{N} = 8$  supersymmetry.
- All models can be rewritten as gauge theories.

⇒ We need more input from physics.

Particularly important here: **AdS/CFT correspondence**

We need some kind of  $N \rightarrow \infty$  limit, so let's look at representations of (generalized) 3-Lie algebras in terms of matrix algebras.

# Classifications of $\ast$ -Algebra Representations of 3-Algebras

Representations on matrix algebras, which are useful for  $N \rightarrow \infty$ , can be constructed.

Representation of metric 3-algebras on  $\ast$ -algebras:

Take a  $\ast$ - or **matrix algebra** equipped with a trace form. Construct a 3-bracket on this algebra from matrix products and the involution and use the Hilbert-Schmidt scalar product  $(A, B) = \text{tr}(A^\dagger B)$ .

Classification of all such representations in the real and hermitian case using MuPad done in [Cherkis, Dotsenko, CS, 0812.3127](#)

# Classifications of $\ast$ -Algebra Representations of 3-Algebras

Representations on matrix algebras, which are useful for  $N \rightarrow \infty$ , can be constructed.

The **Real case**.  $[A, B, C] :=$

$$\text{I} : \alpha([A^\dagger, B], C) + [[A, B^\dagger], C] + [[A, B], C^\dagger] - [[A^\dagger, B^\dagger], C^\dagger])$$

$$\text{II} : \alpha([A, B^\dagger], C) + [[A^\dagger, B], C])$$

$$\text{III} : \alpha(AB^\dagger - BA^\dagger)C + \beta C(A^\dagger B - B^\dagger A)$$

$$\text{IV} : \alpha([A, B], C) + [[A^\dagger, B^\dagger], C] + [[A^\dagger, B], C^\dagger] + [[A, B^\dagger], C^\dagger]) \\ + \beta([A, B], C^\dagger) + [[A^\dagger, B], C] + [[A, B^\dagger], C] + [[A^\dagger, B^\dagger], C^\dagger]) .$$

The class of examples  $\mathcal{C}_{2d}$ ,

$$[\gamma_a, \gamma_b, \gamma_c] := [[\gamma_a, \gamma_b]\gamma_{ch}, \gamma_c] ,$$

is contained in **III**, with  $\alpha = \beta = -1$  and the  $\ast$ -algebra is the algebra of  $d \times d$  matrices.



# Classifications of $\ast$ -Algebra Representations of 3-Algebras

Representations on matrix algebras, which are useful for  $N \rightarrow \infty$ , can be constructed.

The **Hermitian case**.  $[A, B, C] :=$

$$I_\alpha : A, B, C \mapsto \alpha(AC^\dagger B - BC^\dagger A) .$$

This is precisely the Hermitian 3-Lie algebra used in [Bagger, Lambert, 0807.0163](#) to obtain the ABJM model in 3-algebra form.

# Associated 3-products

Analogously to matrix products, one can introduce 3-products.

Recall:

In gauge theories: gauge fields live in Lie algebra, matter fields live in representations of this Lie algebra.

Representations can carry (additional) products, e.g. the adjoint:

$$A \star_{a,b} B = aAB + bBA$$

which still transform covariantly under gauge transformations:

$$\delta_{\Lambda}(A \star_{a,b} B) = \delta_{\Lambda}(A) \star_{a,b} B + A \star_{a,b} \delta_{\Lambda}(B)$$

These are used in the superpotential of  $\mathcal{N} = 1^*$  SYM theory.

# Associated 3-products

Analogously to matrix products, one can introduce 3-products.

Assume now: Matter fields of BLG in **representation**  $\mathcal{R}$  of  $\mathcal{A}$ .

A generalized or associated 3-product is a map

$$\langle A, B, C \rangle : \mathcal{R} \times \mathcal{R} \times \mathcal{R} \rightarrow \mathcal{R}$$

and has to satisfy (real 3-Lie algebras):

$$\begin{aligned} [A, B, \langle C, D, E \rangle] = \\ \langle [A, B, C], D, E \rangle + \langle C, [A, B, D], E \rangle + \langle C, D, [A, B, E] \rangle \end{aligned}$$

Use these products: more general terms in BLG action:

$$\begin{aligned} \mathcal{L} = \int d^4\theta \kappa \left( i \langle V, (\bar{D}_\alpha D^\alpha V) \rangle + \frac{2}{3} \langle V, \{ (\bar{D}^\alpha V), (D_\alpha V) \} \rangle \right) \\ + \langle \bar{\Phi}_i, e^{2iV} \cdot \Phi^i \rangle + \alpha \left( \int d^2\theta \varepsilon_{ijkl} ([\Phi^i, \Phi^j, \Phi^k], \Phi^l) + c.c. \right) \end{aligned}$$

# Which associated 3-products exist in the representations?

The admissible classes of associated 3-products are limited.

## Real 3-algebras:

Class III:  $[A, B, C] := \alpha(AB^\dagger - BA^\dagger)C + \beta C(A^\dagger B - B^\dagger A)$

Most general associated 3-product:

$$\langle A, B, C \rangle = \alpha_1 AB^T C + \alpha_2 CB^T A + \beta_1 BC^T A + \beta_2 AC^T B + \gamma_1 CA^T B + \gamma_2 BA^T C$$

## Hermitian 3-algebras:

Class I:  $[A, B, C] := \alpha(AC^\dagger B - BC^\dagger A)$

Most general associated 3-product:

$$\langle A, B; C \rangle = \alpha_1 AC^\dagger B - \alpha_2 BC^\dagger A$$

- **Introductory part**
  - The **Nahm** equation or **D1-D3** branes
  - The **Basu-Harvey** equation or **M2-M5** branes
  - **3-Lie algebras**
  - **Stacks** of flat **M2**-branes: The **BLG** model
  - **Superspace** formulations
  - **Motivation**: Marginal deformations of  $\mathcal{N} = 4$  **SYM theory**
- **More on 3-algebras**
  - **Real** and **Hermitian** 3-algebras
  - **Matrix** representations of 3-algebras
  - Associated **3-products**
- ▶ **Deformations** preserving  $\mathcal{N} = 2$  supersymmetry
  - Action in terms of  $\mathcal{N} = 2$  **superfields**
  - **Supergraph** Feynman rules
  - Results at two loops
- **Conclusions**

# Action in terms of $\mathcal{N} = 2$ superfields

We generalize the superpotential, using associated 3-products and multitraces.

Real case:

$$S_0^R = i\sqrt{\kappa} \int d^{3|4}z \int_0^1 dt \left( (V, \bar{D}^\alpha (e^{-\frac{2i}{\sqrt{\kappa}}tV} D_\alpha e^{\frac{2i}{\sqrt{\kappa}}tV})) \right) + \int d^{3|4}z (\bar{\Phi}_i, e^{-\frac{2i}{\sqrt{\kappa}}V} \Phi^i)$$

Superpotential:

$$S_1^R = \int d^{3|2}z \left[ R_{ijkl}^{(1)}(\Phi^l, [\Phi^i, \Phi^j, \Phi^k]) + R_{ijkl}^{(2)}(\Phi^i, \Phi^j)(\Phi^k, \Phi^l) \right] + \int d^{3|2}\bar{z} \left[ R_{(1)}^{ijkl}(\bar{\Phi}_l, [\bar{\Phi}_i, \bar{\Phi}_j, \bar{\Phi}_k]) + R_{(2)}^{ijkl}(\bar{\Phi}_i, \bar{\Phi}_j)(\bar{\Phi}_k, \bar{\Phi}_l) \right]$$

Here, we restrict ourselves to multitraces, as the ordinary 3-bracket already allows for marginal deformations.

# Action in terms of $\mathcal{N} = 2$ superfields

We generalize the superpotential, using associated 3-products and multitraces.

## Hermitian case:

Technical issue:  $SU(4)$  R-symmetry does not respect chirality:

$SU(4)$  multiplet:  $(\Phi^m, \bar{\Phi}_{\dot{m}})$ ,  $m, \dot{m} = 1, 2$  and thus:

$$S_0^H = i\sqrt{\kappa} \int d^3|4z \int_0^1 dt \left( (V, \bar{D}^\alpha (e^{-\frac{2i}{\sqrt{\kappa}}tV} D_\alpha e^{\frac{2i}{\sqrt{\kappa}}tV})) \right) \\ + \int d^3|4z \left[ (\Phi^m, e^{-\frac{2i}{\sqrt{\kappa}}V} \Phi^m) + (\bar{\Phi}_{\dot{m}}, e^{\frac{2i}{\sqrt{\kappa}}V} \bar{\Phi}_{\dot{m}}) \right]$$

Superpotential:

$$S_1^H = \int d^3|2z \left[ H_{mn\dot{m}\dot{n}}^{(1)}(\bar{\Phi}_{\dot{n}}, [\Phi^m, \Phi^n; \bar{\Phi}_{\dot{m}}]_\beta) + \right. \\ \left. H_{mn\dot{m}\dot{n}}^{(2)}(\bar{\Phi}_{\dot{m}}, \Phi^m)(\bar{\Phi}_{\dot{n}}, \Phi^n) \right] + c.c.$$

where we defined  $[\tau_a, \tau_b; \tau_c]_\beta := e^{i\beta} \tau_a \tau_c^\dagger \tau_b - e^{-i\beta} \tau_b \tau_c^\dagger \tau_a$ .

# $\mathcal{N} = 2$ Superfield Feynman Rules

Supergraph rules can be derived in a straightforward manner.

Super Feynman rules for Chern-Simons theory with matter are easily derived, see e.g. [S.J. Gates, H. Nishino, PLB281 \(1992\) 72](#)

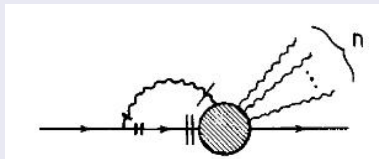
Gluon propagator (Landau gauge):  $\frac{i\bar{D}^\alpha D_\alpha(p, \theta^1)}{p^2} \delta^4(\theta^1 - \theta^2)$

Matter propagator:  $\frac{1}{p^2} \delta^4(\theta^1 - \theta^2)$

Vertices: from action, insert  $-\frac{1}{4}\bar{D}^2 / -\frac{1}{4}D^2$  for  $\Phi / \bar{\Phi}$   
add the usual **loop integrals**, **symmetry factors**, ...

## Vanishing lemma

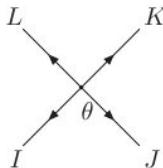
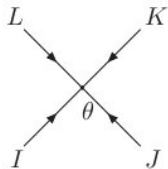
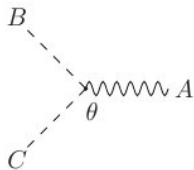
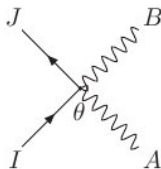
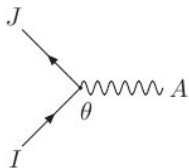
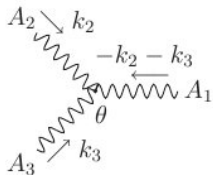
The following diagrams essentially vanish due to  $D^3 = \bar{D}^3 = 0$ :





# Types of vertices for 2-loop computations

Of the infinite vertices, only finitely many contribute at 2-loop level.

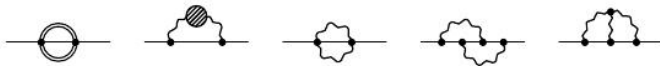


# Advantages of using $\mathcal{N} = 2$ SUSY Formulation

Perturbative calculations are much simpler using supergraphs.

**Example:** Field strength renormalization.

In components: [Gaiotto, Yin, JHEP 08 \(2007\) 056](#)

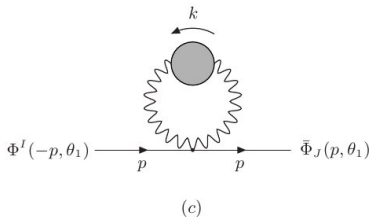
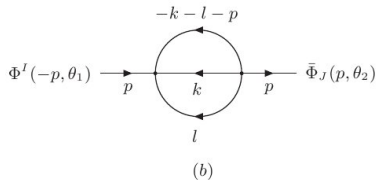
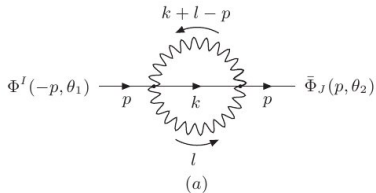


With **supergraphs**, only the 1st and 3rd diagrams survives (lemma).

# Contributing diagrams

At 2 loop level, only three classes of diagrams contribute.

Contributing diagrams (only 2-pt contributions are divergent):



Potential flow of the couplings due to **anomalous dimensions**.

# Casimirs

Casimir invariants are computed in certain representations.

2nd reason for matrix representations: Need to compute Casimirs.

Introduce  $f_{abcd} = (\tau_d, [\tau_a, \tau_b, \tau_c])$  and  $h_{ab} = (\tau_a, \tau_b)$ . Examples:

$$f_{ac}{}^{cb} = c_1 \delta_a{}^b \quad f_{acde} f^{edcb} = -c_2 \delta_a{}^b \quad f_{acde} f^{bcde} = -c_3 \delta_a{}^b$$

and similar objects on the associated Lie algebras  $\mathfrak{g}_A$ .

These can easily be computed in  $\mathfrak{u}(N)$  and  $\mathfrak{so}(N)$ , e.g.

$$\mathrm{tr}(\tau_a^T \tau_b) = \delta_{ab} =: h_{ab} \quad \text{and} \quad (\tau_a)_{ij} (\tau_a)_{kl} = \delta_{ik} \delta_{jl}$$

for  $\mathfrak{so}(N)$ .

# Results: The $\beta$ -function in the real case

The BLG model is conformally invariant at two loops.

**Recall:** All flow from anomalous dimensions at two loops.

Total anomalous dimension:

$$\gamma_i^j = \frac{1}{8\pi^2\kappa^2} \left\{ \left[ k_2 + k_1^2 + \frac{1}{12}(2k_2 + N_f k_3) \right] \delta_i^j \right. \\ \left. + 8\kappa^2 \left[ R_{iklm}^{(1)} \left( -c_3 R_{(1)}^{jklm} + 2c_2 R_{(1)}^{jmlk} + 2c_1 R_{(2)}^{jmlk} \right) \right. \right. \\ \left. \left. + R_{iklm}^{(2)} \left( d R_{(2)}^{jklm} + 2R_{(2)}^{jmlk} + 2c_1 R_{(1)}^{jmlk} \right) \right] \right\}$$

Quick test: **BLG**.  $R_{ijkl}^{(2)} = 0$ ,  $\mathcal{A} = A_4$ , therefore  $R_{ijkl}^{(1)} = \lambda \varepsilon_{ijkl}$  and

$$d = 4 \quad k_1 = 0 \quad k_2 = -3 \quad k_3 = 6 \quad c_1 = 0 \quad c_2 = c_3 = -6$$

The  $\beta$ -function reads as (the phase does not flow)

$$\beta_{ijkl}^{(1)} = -\frac{3}{4\pi^2\kappa^2} [1 - (4!\kappa)^2 |\lambda|^2] R_{ijkl}^{(1)} \quad \text{so} \quad |\lambda| = \frac{1}{4!\kappa}$$

At point where  $\beta_{ijkl}^{(1)} = 0$ , regularization scheme **irrelevant**.

# Results: The $\beta$ -function in the hermitian case

The ABJM model is conformally invariant at two loops.

$$\begin{aligned} \gamma_m^n = & \frac{1}{8\pi^2\kappa^2} \left\{ [k_2 + k_1^2 + \frac{1}{12}(2k_2 + N_f k_3)] \delta_m^n \right. \\ & + \kappa^2 \left[ (H_{mk\dot{m}\dot{n}}^{(1)} H_{(1)}^{\dot{m}\dot{n}kn} - H_{mk\dot{m}\dot{n}}^{(1)} H_{(1)}^{\dot{n}\dot{m}kn}) c_2 \cos^2 \beta \right. \\ & + (H_{mk\dot{m}\dot{n}}^{(1)} H_{(1)}^{\dot{m}\dot{n}kn} + H_{mk\dot{m}\dot{n}}^{(1)} H_{(1)}^{\dot{n}\dot{m}kn}) c_2' \sin^2 \beta \\ & + (H_{mk\dot{m}\dot{n}}^{(1)} H_{(2)}^{\dot{m}\dot{n}kn} + H_{mk\dot{m}\dot{n}}^{(2)} H_{(1)}^{\dot{m}\dot{n}kn}) (c_1 \cos \beta + ic_1' \sin \beta) \\ & - (H_{mk\dot{m}\dot{n}}^{(1)} H_{(2)}^{\dot{n}\dot{m}kn} + H_{mk\dot{m}\dot{n}}^{(2)} H_{(1)}^{\dot{n}\dot{m}kn}) (c_1 \cos \beta - ic_1' \sin \beta) \\ & \left. \left. + (H_{mk\dot{m}\dot{n}}^{(2)} H_{(2)}^{\dot{m}\dot{n}kn} + d H_{mk\dot{m}\dot{n}}^{(2)} H_{(2)}^{\dot{n}\dot{m}kn}) \right] \right\} \end{aligned}$$

Quick test: **ABJM**.  $\beta = 0$ ,  $N_f = 4$   $H_{mn\dot{m}\dot{n}}^{(1)} = \lambda \varepsilon_{mn} \varepsilon_{\dot{m}\dot{n}}$ ,  $H_{ijkl}^{(2)} = 0$

The  $\beta$ -function reads as

$$\gamma_m^n = \frac{1}{16\pi^2\kappa^2} (1 - N^2) [1 - (4\kappa)^2 |\lambda|^2] \delta_m^n \quad \text{so} \quad |\lambda| = \frac{1}{4\kappa}$$

# Discussion of results

The running of the coupling is exactly as expected.

**Real case:**

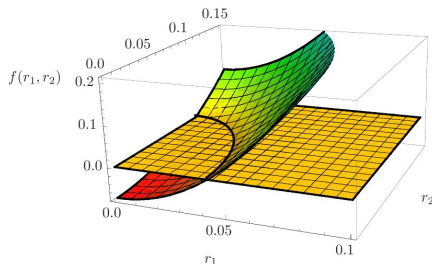
For simplicity, we take  $\mathcal{A} = A_4$  and the superpotential

$$R_{ijkl}^{(1)} = \frac{\lambda_1}{\kappa} \varepsilon_{ijkl} \quad \text{and} \quad R_{ijkl}^{(2)} = \frac{\lambda_2}{\kappa} \delta_{ij} \delta_{kl}, \quad \lambda_i = r_i e^{i\varphi_i}$$

The  $\beta$ -function at two loops reads as

$$\beta_{ijkl}^{(\ell)} = \frac{f(r_1, r_2)}{\kappa^2} R_{ijkl}^{(\ell)} \quad f(r_1, r_2) := -\frac{3}{4\pi^2} [1 - 96(6r_1^2 + r_2^2)]$$

(again, the phases do not flow)



BLG:  $r_1 = \frac{1}{24}, r_2 = 0$

points on ellipse:

**IR fixed points**

similar for hermitian case

# Conclusions

## Summary and Outlook.

### Done:

- Identification of **extended 3-algebraic structures**
- **Verified conformal invariance** up to 2 loops for BLG/ABJM
- Found classes of **marginal deformations**

### Future directions:

- **Other** representations?
- Finiteness **to all orders** in perturbation theory?
- **Integrability** for subsectors?
- Identify **dual geometries**
- **$\hbar$**  deformations?



# Marginal Deformations and 3-Algebra Structures

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25th North British Mathematical Physics Seminar and  
10th Anniversary of the EMPG, Sep 30th 2009